

MVB-TCMS

Datasheet

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Foreword

Notational Conventions

The following categorized signal words with defined meaning might appear in the manual.







Signal Words	Meaning
 DANGER	Indicates a high potential hazard which, if not avoided, will result in death or serious injury.
 CAUTION	Indicates a potential risk which, if not avoided, could result in property damage, data loss, lower performance, or unpredictable result.
 ANTISTATIC	Indicates static sensitive equipment.
 DANGER! ELECTRIC SHOCK	Indicates High voltage danger.
 TIPS	Provides methods to help you solve a problem or save you time.
 NOTE	Provides additional information as the emphasis and supplement to the text.

Table of Contents

Foreword	I
1 Overview	4
1.1 Introduction	4
1.2 Applications	4
1.3 Features	5
1.4 Order Information	5
1.5 Function Blocks	6
1.6 Technical Specifications	7
2 Hardware and Physical Interface	9
2.1 Appearance	9
2.2 LED Indicators	9
2.3 Ethernet Interfaces ETH1, ETH2 (X10, X11)	9
2.3.1 Function Description	9
2.3.2 Pin Definition	10
2.4 MVB Interface S1(X20, X21)	10
2.4.1 ESD+ Pin Definition	10
2.4.2 EMD Pin Definition	10
2.5 RS-232/422/485 Interface S3 (X3)	11
2.5.1 Function Description	11
2.5.2 Pin Definition	11
2.5.3 RS-485 Terminal Matching	11
2.6 CAN/RS-422/RS-485 Interface S4 (X4)	12
2.6.1 Function Description	12
2.6.2 Pin Definition	12
2.6.3 CAN bus Terminal Matching	12
2.6.4 RS-485 Terminal Matching	12
2.7 Power Interface (X5)	13
2.7.1 Function Description	13
2.7.2 Pin Definition	13
3 Building Configuration Environment	14
3.1 Connect Management Computer to MVB-TCMS	14
3.2 Get Configuration Management Software yacer-DMS	14
3.3 Run yacer-DMS software	14
3.4 Main Window of yacer-DMS	15
3.5 Statistical Report	16
3.5.1 Control Panel	16
3.5.2 Receive/Transmit Indication Panel	16
3.5.3 Information Panel	16
3.6 Configure Device	17
4 Function and Configuration	18
4.1 Ethernet Configuration	18

4.1.1 Ethernet Interface Working Mode.....	18
4.1.2 Enable Ethernet Switch	18
4.1.3 Dual IP Configuration.....	19
4.1.4 Default Gateway	20
4.2 Interface Configuration.....	21
4.2.1 Function Description	21
4.2.2 MVB Interface Configuration	21
4.2.3 Serial Configuration	22
4.2.4 MVB to Serial.....	25
4.3 UDP Configuration	26
4.3.1 Function Description	26
4.3.2 UDP to Interface	26
4.3.3 Interface to UDP	27
4.4 MVB-PD Configuration.....	28
4.4.1 Sink Port to Ethernet.....	28
4.4.2 Sink Port to Serial	28
4.4.3 Serial Pull Mode.....	29
4.5 TRDP-PD Configuration.....	30
4.5.1 Function Description	30
4.5.2 TRDP-PD Subscribe.....	30
4.5.3 TRDP-PD Publish	30
5 System Maintenance.....	31
5.1 Firmware Version Upgrade	31
5.1.1 Start Upgrade	31
5.1.2 Select Version File	31
5.1.3 Complete Upgrade.....	32
5.1.4 Confirm Upgrade	32
5.2 Reboot Device.....	33
5.3 Ping	33
6 Mechanical Data	34
7 Verification and Debugging of MVB	35
7.1 Auxiliary Equipment	35
7.2 Auxiliary Software.....	35
7.3 Debugging and Testing Scheme.....	35
8 Software Development.....	36
8.1 MVB Data Format Conversion.....	36
8.2 TRDP Data Format Conversion.....	36
8.3 CAN Data Format Conversion	36

1 Overview

1.1 Introduction

The Yacer MVB-TCMS TCN protocol converter provides MVB interface, two 100M Ethernet interfaces and two extended interfaces to implement protocol conversion between MVB, serial port, CAN bus and Ethernet, and optionally supports TRDP protocol.

Industrial wide temperature, complete isolation and protection, compact size, suitable for train communication network.



1.2 Applications

- Protocol conversion between MVB and Ethernet interface;
- Protocol conversion between MVB and Serial interface;
- Protocol conversion between Serial and Ethernet interface;
- Protocol conversion between CAN and Ethernet interface;
- Protocol conversion between TRDP and UDP;
- Protocol conversion between TRDP and Serial interface;
- Train Communication Network (TCN);
- Train Control and Management System (TCMS);
- Embedded development and application.

1.3 Features

- MVB redundant interface, supporting ESD +, EMD interface;
- Compliance with IEC61375 standard;
- Two 10/100M Ethernet interfaces, optionally supporting TRDP protocol;
- X3 extended interface: Optional RS-232, RS-422 or RS-485 serial port;
- X4 extended interface: Optional RS-422, RS-485 serial port or CAN bus;
- Perfect isolation protection;
- Industrial wide temperature.

1.4 Order Information

MVB-TCMS	-	M	3	5	U	-	LV
MVB Type:							
• EMD		M					
• ESD+		S					
X3 extended interface:							
• None			0				
• Full-duplex RS-232			3				
• Full-duplex RS-422			4				
• Half-duplex RS-485			5				
X4 extended interface:							
• None				0			
• Full-duplex RS-422				4			
• Half-duplex RS-485				5			
• CAN bus interface				6			
UDP/TRDP support:							
• Ethernet supports UDP protocol					U		
• Ethernet supports UDP, TRDP protocol					T		
Supply voltage range:							
• Nominal 24V, tolerance 9 ~ 36VDC							LV
• Nominal 36V, 48V, tolerance 18 ~ 75VDC							MV
• Nominal 72V,96V,110V, tolerance 40 ~ 160VDC							HV

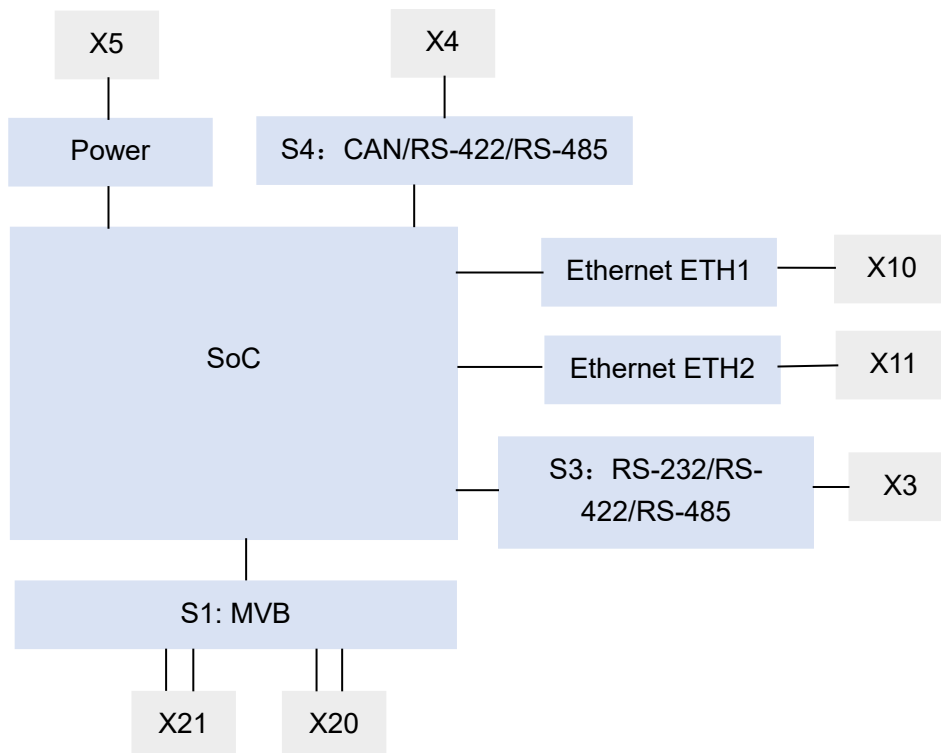


If you need to add onboard application CPU for onboard programming, please contact us.

1.5 Function Blocks

The basic function blocks are shown in the following figure:

- X20, X21 are MVB dual line redundant interfaces S1;
- X3 is the expansion interface S3, optionally RS-232, RS-422 or RS-485;
- X4 is the expansion interface S4, optionally CAN, RS-422 or RS-485;
- ETH1, ETH2 are two 100M Ethernet ports, which are connected to connectors X10 and X11 respectively.
- X5 is the power connector.



1.6 Technical Specifications

Item	Parameters	Details
S1 MVB Interface	Connector	1 x male D-Sub 9 (X20) + 1 x female D-Sub 9 (X21)
	Media type	Optional EMD, ESD+
	Device Class	Class 1
	Device Capabilities	Device_Status, Process_Data(PD)
	Number of PD ports	1024
	Isolation	2.5 kVrms
Extended Interface S3	Connector	1 x male D-Sub 9 (X3)
	Interface type (three-choice)	<ul style="list-style-type: none"> ● RS-232 full-duplex serial ● RS-422 full-duplex isolated serial ● RS-485 half-duplex isolated serial
	Baud rate	Asynchronous ≤ 1 Mbps
	Isolation	2.5 kVrms
Extended Interface S4	Connector	1 x male D-Sub 9 (X4)
	Interface type (three-choice)	<ul style="list-style-type: none"> ● CAN bus isolation interface(CAN2.0A, CAN2.0B, ISO 11898) ● RS-422 full-duplex isolated serial ● RS-485 half-duplex isolated serial
	Baud rate	UART ≤ 1 Mbps CAN: 50 Kbps ~ 1 Mbps
	Isolation	2.5 kVrms
Ethernet Interface	Connector	2 x M12 with D-coding
	Function	Ethernet switching, dual-IP function
	Rate	10/100 Mbps adaptive, Forced 100 Mbps
	Protocol	TCP/IP, optionally supporting TRDP
	Programming interface	UDP Server, UDP Client Unicast/Multicast/Broadcast
	Isolation	1.5 kVrms

Item	Parameters	Details
Configuration Management	Configuration tool	yacer-DMS configuration management software
	Configuration interface	Ethernet Interface, optional serial port
Power Requirements	Power Supply	LV: Nominal 24V, tolerance 9 ~ 36VDC MV: Nominal 36V, 48V, tolerance 18 ~ 75VDC HV: Nominal 72V, 96V, 110V, tolerance 40 ~ 160VDC
	Isolation protection	>1.5 kV, Anti-reverse protection
	Power consumption	< 3 W
	Connector	3 pin connector with 5mm pitch (Phoenix Contact MSTB 2,5 / 3-GF or equivalent)
Mechanical Characteristics	Dimensions	H x W x D: 124 mm x 36 mm x 104 mm
	Weight	500g
Operating Environment	Operating temperature	-40 ~ +70°C
	Storage temperature	-40 ~ +85°C
	Operating humidity	5 ~ 95% RH (no condensation)

2 Hardware and Physical Interface

2.1 Appearance



2.2 LED Indicators

LED	Description
RUN	Running indicator, flashing during normal operation
ALARM	Alarm indicator, on when the device is not ready or fails, and constantly off during normal operation
MVB A	MVB interface A line transceiver instructions
MVB B	MVB interface B line transceiver instructions
X3	Extension interface S3 transceiver instructions
X4	Extension interface S4 transceiver instructions
LINK/ACT	Link/ACT indication of Ethernet interfaces

2.3 Ethernet Interfaces ETH1, ETH2 (X10, X11)

2.3.1 Function Description

ETH1, ETH2 are two 10/100M Ethernet interfaces with connectors X10 and X11 as M12 (D-coding).

There are two working modes for the Ethernet interfaces:

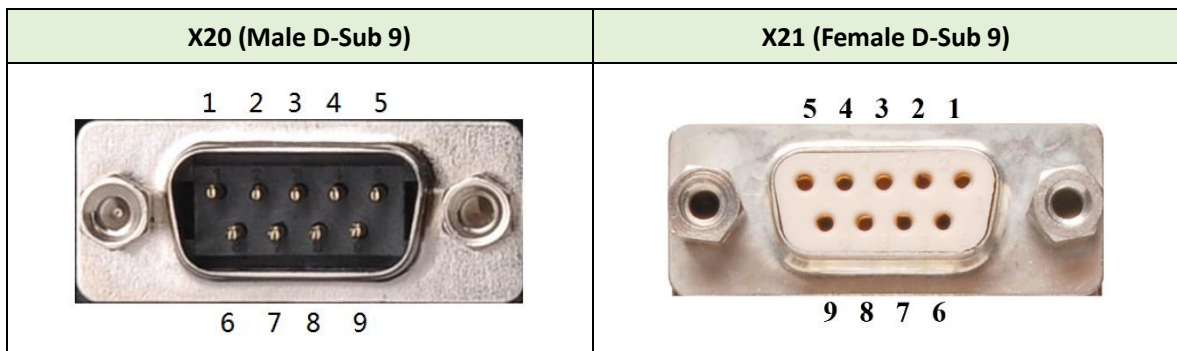
- Ethernet switching mode: Enable the built-in Ethernet switching function;
- Dual IP mode: Each Ethernet interface has an independent IP address.

2.3.2 Pin Definition

X10, X11 Pin	Description
1	TD +
2	RD +
3	TD -
4	RD -



2.4 MVB Interface S1(X20, X21)



2.4.1 ESD+ Pin Definition

Pin	X20 (Male)	X21 (Female)	Description
1	A.Data_P		Line A positive (+)
2	A.Data_N		Line A negative (-)
3			
4	B.Data_P		Line B positive (+)
5	B.Data_N		Line B negative (+)
6	A.Bus_GND		Line A grounding
7	B.Bus_GND		Line B grounding
8	A.Bus_5V		Line A power supply
9	B.Bus_5V		Line B power supply

2.4.2 EMD Pin Definition

Pin	X20 (Male)	X21 (Female)	Description
1	A.Data_P		Line A positive (+)
2	A.Data_N		Line A negative (-)
3			
4	B.Data_P		Line B positive (+)

Pin	X20 (Male)	X21 (Female)	Description
5	B.Data_N		Line B negative (+)
6	A.Term_P		Line A matching resistance ancode
7	A.Term_N		Line A matching resistance cathode
8	B.Term_P		Line B matching resistance ancode
9	B.Term_N		Line B matching resistance cathode

2.5 RS-232/422/485 Interface S3 (X3)

2.5.1 Function Description

X3 is an extended serial port, users can choose one of the following types when ordering:

- RS-232 full-duplex;
- RS-422 full-duplex with isolation;
- RS-485 half-duplex with isolation.



2.5.2 Pin Definition

X3 uses male D-Sub 9 male connector, pin defined as follows:

Pin	RS-232 Full Duplex	RS-422 Full Duplex	RS-485 Half Duplex
1			
2	RxD		
3	TxD	ISO_GND	ISO_GND
4		TxD +	Data +
5	GND	TxD -	Data -
6			
7			
8		RxD +	Term +
9		RxD -	Term +

2.5.3 RS-485 Terminal Matching

In RS-485 mode, 8-9 short connection enable terminal matching, matching resistance is 120 ohms.

2.6 CAN/RS-422/RS-485 Interface S4 (X4)

2.6.1 Function Description

X4 is an extended interface, users can choose serial port or CAN bus interface when ordering. When the serial port is configured, one of the following configurations can be selected from the factory:

- RS-422: full-duplex with isolation;
- RS-485: half-duplex with isolation.



2.6.2 Pin Definition

S4 connector X4 uses male D-Sub 9 male connector, pin defined as follows:

Pin	CAN	RS-422 Full Duplex	RS-485 Half Duplex
1	Term +		
2	CAN_L		
3	ISO_GND	ISO_GND	ISO_GND
4		TxD +	Data +
5		TxD -	Data -
6	Term -		
7	CAN_H		
8		RxD +	Term +
9		RxD -	Term -

2.6.3 CAN bus Terminal Matching

In CAN working mode, 1-6 short connection enable terminal matching of CAN bus, matching resistance is 120 ohms.

2.6.4 RS-485 Terminal Matching

In RS-485 mode, 8-9 short connection enable terminal matching, matching resistance is 120 ohms.

2.7 Power Interface (X5)

2.7.1 Function Description

MVB-TCMS is powered by DC power supply, supports isolation protection and surge protection, and provides anti-inverse protection.

Depending on the factory configuration, the power input range is as follows:

Model	Nominal Value	Minimum	Maximum
LV	24V	9V	36V
MV	36V、48V	18V	75V
HV	72V、96V、110V	40V	160V

2.7.2 Pin Definition

The X5 uses a 3-pos 5mm terminal connector (Phoenix Contact MSTB 2,5 / 3-GF compatible).

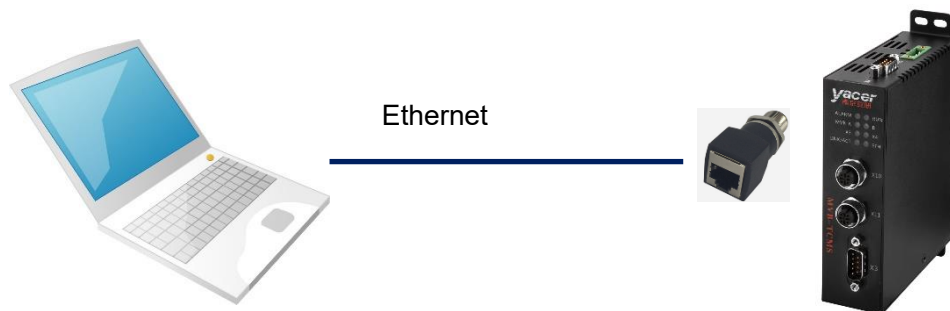
Pin	Signal Name	Description
1	V+	Voltage +
2	CASE	Protection Earth
3	V-	Voltage -



3 Building Configuration Environment

3.1 Connect Management Computer to MVB-TCMS

Connect the management computer with any Ethernet interface port of MVB-TCMS through network cable, and run yacer-DMS configuration management software on the computer to configure the parameters and monitor running status of MVB-TCMS.



If S3 and S4 are serial ports, when configured as DMS-ISP mode, the computer serial port can be connected and configured and managed with yacer-DMS.

3.2 Get Configuration Management Software yacer-DMS

Users can obtain the compressed package yacer-DMS.zip of configuration management software through the following ways:

- “Softwares” directory of MVB-TCMS accompanied U-Disk;
- Official website of Yacer (<http://www.yacer.com.cn>) Software channel.

3.3 Run yacer-DMS software

The yacer-DMS is an installation free application software, unzip yacer-DMS.zip, enter the working directory and double click the file yacer-DMS.exe to run.

3.4 Main Window of yacer-DMS

The following figure is the main interface of the configuration management software, which can be divided into three parts:

- **Toolbar:** Functional operation buttons;
- **Device List:** Displaying the basic information and operation status of online devices;
- **Statistical Report:** Displaying the receive/transmit indication & statistics, and device details.

Status	Model	S/N	IP Address	Alias
1 OK	MVB-TCMS-M36T-LV	8Y21C07823	192.168.2.200	

MVB-TCMS-M36T-LV Report Refresh Period: seconds Refresh Clear

	Tx	Rx
S1	<input type="radio"/>	<input type="radio"/>
S3	<input type="radio"/>	<input type="radio"/>
S4	<input type="radio"/>	<input type="radio"/>

Statistical Report

MVB-TCMS-M36T-LV Information
 Running time: 4h 13m 55s
 Device S/N: 8Y21C07823 IP Address: 192.168.2.200
 Hardware Version: 2.3 FPGA Version: 2021.0313 Firmware Version: 2021.0809

MVB
 Device Status : 0xC0; LAT RLD
 Switchover = 120, T_switchover

Interface
 S1: MVB EMD, Tx = 0, Rx = 0
 S3: RS-232, Tx = 0, Rx = 0
 S4: CAN, Tx = 0, Rx = 0, Normal, Idle, Active, 75%

TRDP v2.1.22.56
 Tx = 0
 Rx = 0

UDP
 Tx = 0
 Rx = 0

DMS Service

3.5 Statistical Report

The statistical report has three panels: control panel, receive/transmit indication panel and information panel.

3.5.1 Control Panel

MVB-TCMS-M36U-LV Report Refresh Period: seconds

Control Widget	Function
Refresh Period: <input type="text" value="1"/> seconds	Statistical report refresh cycle
<input type="button" value="Refresh"/>	Manual refresh operation
<input type="button" value="Clear"/>	Clear the statistical report

3.5.2 Receive/Transmit Indication Panel

- Tx: The interface sends a frame of data, corresponding Tx indicator blinks once;
- Rx: The interface receives a frame of data, corresponding Rx indicator blinks once.

	Tx	Rx	
S1	<input type="checkbox"/>	<input type="checkbox"/>	
S3	<input type="checkbox"/>	<input type="checkbox"/>	
S4	<input type="checkbox"/>	<input type="checkbox"/>	

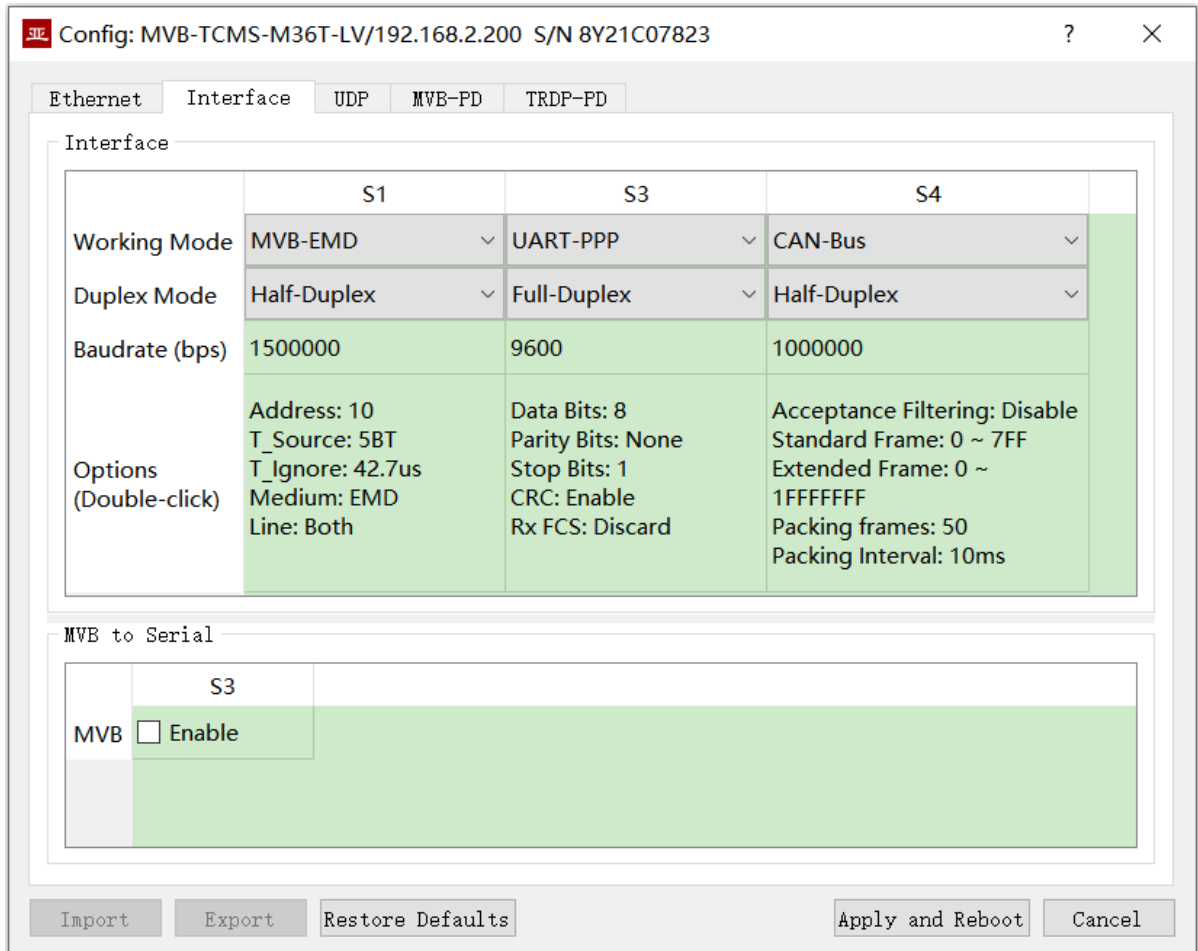
3.5.3 Information Panel

The right side of the statistical report is the information panel, which can display the following contents:


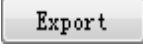
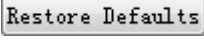
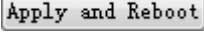
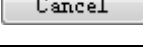
- Device information: Running time, S/N number, version number;
- MVB: MVB interface status information;
- Interface: Receive/transmit statistics of MVB, Serial, CAN and other interfaces;
- TRDP: Receive/transmit statistics of TRDP protocol;
- UDP: Receive/transmit statistics of UDP;
- DMS Service: DMS message receive/transmit statistics.

3.6 Configure Device

Click the 'Config' button on the toolbar or double-click the selected device in the device list, DMS pops up the configuration dialog. According to the interface and function, the dialog divides the configuration items into several configuration pages.



The bottom of the dialog box includes the following operation buttons:

Button	Function
	Open the configuration file, read the configuration parameters refresh the configuration dialog
	Export configuration parameters from the configuration dialog to a file for saving
	Refresh the configuration dialog with the factory parameters
	Write the configuration parameters in the dialog to the device, and restart the device to make the configuration take effect
	Cancel current configuration operation

4 Function and Configuration

4.1 Ethernet Configuration

4.1.1 Ethernet Interface Working Mode

Ethernet interface can choose auto negotiation or mandatory 100M full-duplex mode.

The Ethernet interface that supports the TRDP protocol, whose speed mode is forced to 100M full-duplex.

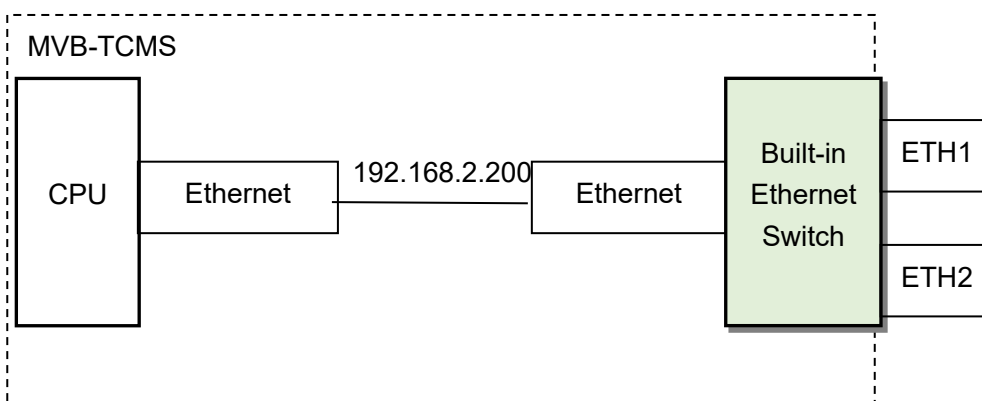
Ethernet						
Interface						
UDP						
MVB-PD						
TRDP-PD						
<input type="checkbox"/> Enable Ethernet Switch						
	IP Address	Subnet Mask	Default Gateway	Speed	Protocol	
ETH1	192.168.2.200	255.255.255.0	0.0.0.0	100M Full-duplex	TRDP	
ETH2	192.168.3.200	255.255.255.0	0.0.0.0	Auto Negotiation	UDP	
				Auto Negotiation		
				100M Full-duplex		

4.1.2 Enable Ethernet Switch

By default, check the “Enable ethernet switch” checkbox to enable the built-in Ethernet switch, to provide Ethernet switching function between ETH1 and ETH2.

<input checked="" type="checkbox"/> Enable ethernet switch						
	IP Address	Subnet Mask	Default Gateway	Speed		
ETH1	192.168.2.200	255.255.255.0	0.0.0.0	Auto Negotiation		

After enabling the Ethernet switching function, MVB-TCMS only has one IP address. The network functions are as follows:



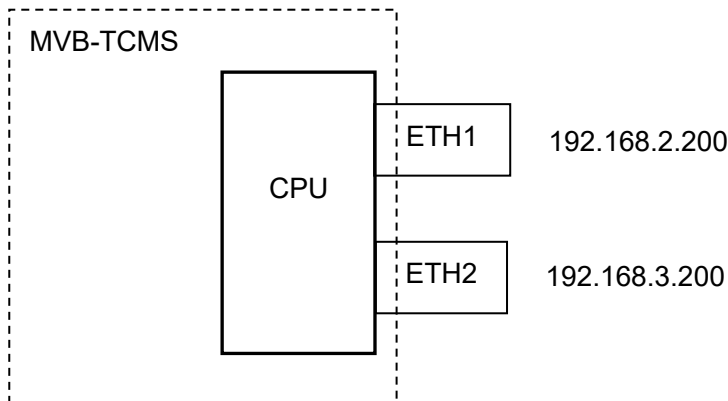
4.1.3 Dual IP Configuration

When the “Enable ethernet switch” checkbox is unchecked, ensure ETH1 and ETH2 are not on the same subnet for configuration as they have an independent IP address.

Enable ethernet switch

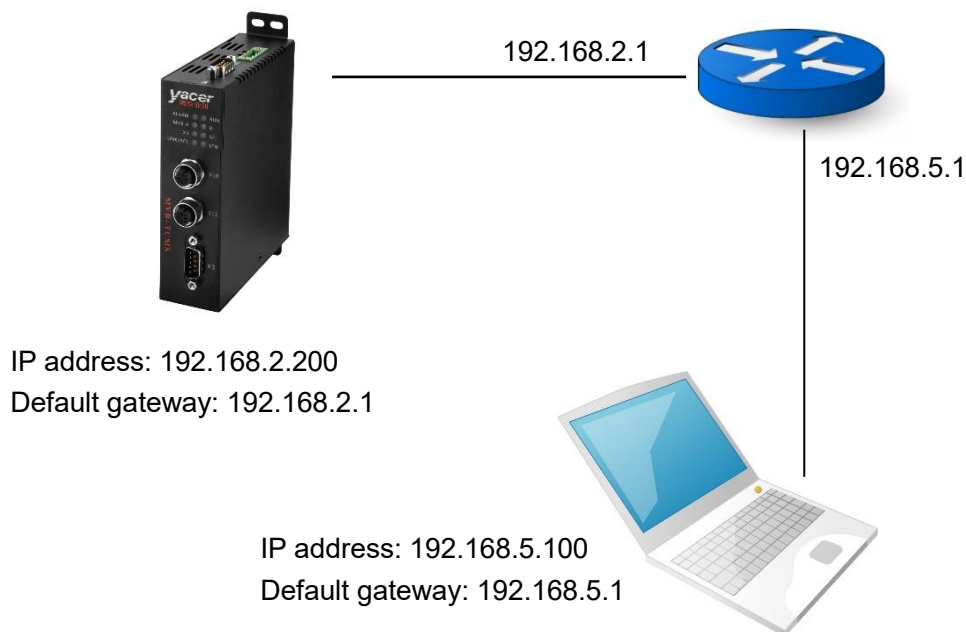
	IP Address	Subnet Mask	Default Gateway	Speed
ETH1	192.168.2.200	255.255.255.0	0.0.0.0	Auto Negotiation ▼
ETH2	192.168.3.200	255.255.255.0	0.0.0.0	Auto Negotiation ▼

With the dual-IP function figure as follows, the MVB-TCMS is equivalent to a PC equipped with two network cards.



4.1.4 Default Gateway

By default, the default gateway is 0.0.0.0, representing that there is no gateway configuration. If MVB-TCMS needs to communicate with the host on other subnet, it must rely on an external router. At this time, the MVB-TCMS's IP address must be on the same subnet with the IP address of the connected router port. Meanwhile, the IP address of router is set to the default gateway. As shown below, the IP address of MVB-TCMS and remote PC is 192.168.2.200 and 192.168.5.100 respectively. As they do not belong to the same subnet, they must rely on the router for communication. MVB-TCMS and PC need to set the IP address of the connected router port to the default gateway of this device.



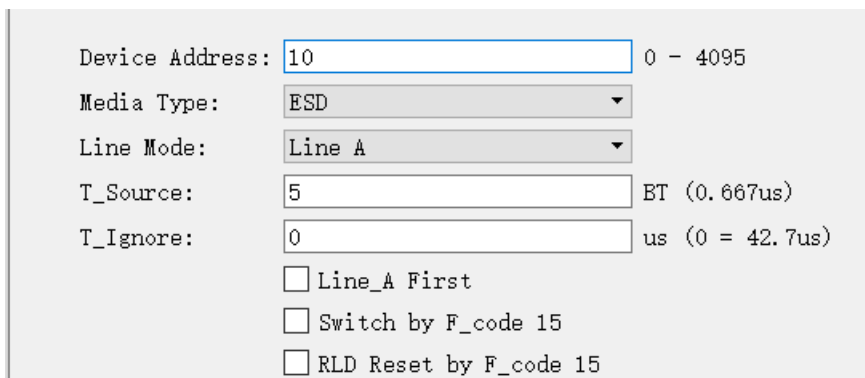
4.2 Interface Configuration

4.2.1 Function Description

This page is used to configure the working mode, duplex mode, baud rate and option parameters of the extended interface (MVB, serial port or CAN port), and can configure the forwarding relationship between MVB and serial port.

4.2.2 MVB Interface Configuration

MVB interface S1 mode of work, duplex mode and baud rate set when factory, users do not need to modify. Double-click the advanced option cell to pop up the MVB parameter configuration dialog.



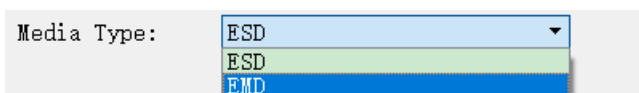
The screenshot shows a configuration dialog box with the following fields and options:

- Device Address: 10 (range 0 - 4095)
- Media Type: ESD (dropdown menu)
- Line Mode: Line A (dropdown menu)
- T_Source: 5 BT (0.667us)
- T_Ignore: 0 us (0 = 42.7us)
- Line_A First
- Switch by F_code 15
- RLD Reset by F_code 15

4.2.2.1 Device Address

Users configure device address in the range of 0 to 4095 according to field requirements.

4.2.2.2 Media Type



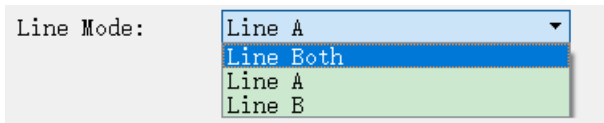
The screenshot shows the Media Type dropdown menu with the following options:

- ESD
- ESD
- EMD

The media type of the logical layer is the same as that of the physical layer by default.

MVB-TCMS allows the use to choose the media type of the logical layer for certain special occasions.

4.2.2.3 Line Type



Users can choose:

- Line Both: double-line redundancy;
- Line A: A line single line mode;
- Line B: B line single line mode.

4.2.2.4 Other Parameters

Using default values, users do not modify or adjust as much as possible.

4.2.3 Serial Configuration

4.2.3.1 Working Mode

The extended interfaces S3 and S4 can be configured as serial ports when leaving the factory. Users can select the desired working mode from the “working mode” combo box.

- UART: Universal asynchronous serial mode, similar to serial port on a universal computer;
- UART-PPP: Frame transmission on UART Interface using PPP protocol;
- DMS-ISP: yacer-DMS configuration management software can use this serial port for management.

Interface	S1	S3	S4
Working Mode	MVB-EMD	UART-PPP	CAN-Bus
Duplex Mode	Half-Duplex	UART-PPP	Half-Duplex
Baudrate (bps)	1500000	1000000	1000000

After determining the working mode, the contents of the “Advanced Options” cell will be adjusted automatically according to the working mode.

If you need to further more configuration of working parameters for the selected working mode, double-click on the “Options” cell to pop up the parameter configuration dialog.

If the MVB interface and the extended serial port are configured to forward each other, the serial port default uses UART-PPP working mode. The UART-PPP working mode encapsulates MVB data and information into frames and transmits them on the asynchronous serial port.

4.2.3.2 UART-PPP Options

Since UART sends and receives character stream without head and tail, in order to transmit an MVB packet, a UART-PPP frame is constructed by adding 0x7E as the start and end flag at the beginning and end of the packet, and inserting a frame check sequence.

Data Bits:	8
Parity Bits:	None
Stop Bits:	1
	<input checked="" type="checkbox"/> CRC Enable
	<input type="checkbox"/> Forward received FCS field

4.2.3.3 UART Options

UART is a type of character stream communication. Data bits, check bits and stop bits define the basic working parameters of asynchronous serial port, which must be identical with the configuration of opposite device.

Generally, data bits are defined as 8 bits (1 byte), so that UART corresponds to the communication of byte streams.

Data Bits:	8
Parity Bits:	None
Stop Bits:	1
Rx Packing Size:	128 bytes
Rx Packing Interval:	10 ms

When converting the byte stream of UART into UDP message, if every byte is converted into a UDP message for transmission, the overhead is too large and the efficiency is too low.

In order to improve the efficiency, MVB-TCMS will buffer the received byte stream, and then send out a UDP message composed of several buffered bytes. This process is called packing.

Packing is controlled by two parameters, which are called Packing Size & Packing interval.

4.2.3.3.1 Packing Size

For example, if the Packing Size is set to 128 bytes, then when UART receives 128 bytes, a packet will be formed for forwarding.

Rx Packing Size:	128 bytes
------------------	-----------

4.2.3.3.2 Packing Interval

For example, the above example sets the Packing Interval to 10ms. If the UART does not receive new data after 10ms, the data in the buffer will be forwarded as a packet regardless of whether 128 bytes are received.

Rx Packing Interval: ms

4.2.3.4 CAN Interface Options

X4 can be selected as CAN bus interface in the factory, and the configuration is as follows:

	<input type="checkbox"/>	Acceptance Filtering	
Standard Frame IDmin	<input type="text" value="0"/>		(Hex)
Standard Frame IDmax	<input type="text" value="7FF"/>		(Hex)
Extended Frame IDmin	<input type="text" value="0"/>		(Hex)
Extended Frame IDmax	<input type="text" value="1FFFFFFF"/>		(Hex)
Rx Packing Frame Number:	<input type="text" value="50"/>		
Rx Packing Interval:	<input type="text" value="10"/>		ms

Because the CAN frame is very short, if each CAN frame is converted into a UDP message for transmission, the overhead is too large and the efficiency is too low.

In order to improve the efficiency, MVB-TCMS buffers the received can frames, and then forwards the buffered CAN frames into a packet, which is called packing.

Packing is controlled by two parameters, which are called Packing Frame Number & Packing interval.

4.2.3.4.1 Packing Frame Number

The maximum Packing Frame Number is 50.

Rx Packing Frame Number:

As shown in the figure above, the Packing Frame Number is 50. When MVB-TCMS receives 50 CAN frames, it is assembled into a data packet for forwarding.

4.2.3.4.2 Packing Interval

As the above example sets the packet splitting interval to 10ms, if no new CAN frame is received for more than 10ms, the CAN frames in the buffer will be composed into one packet for forwarding, regardless of whether 50 frames are received or not.

Rx Packing Interval: ms

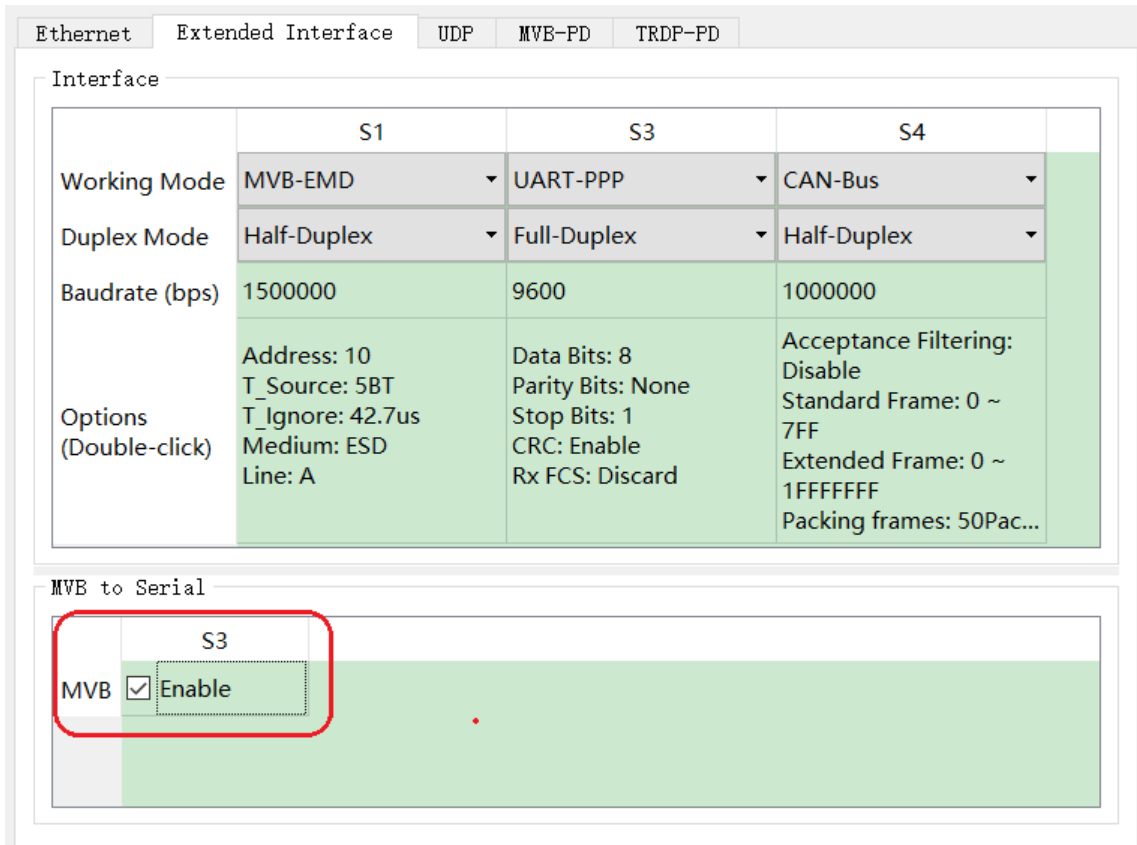
4.2.3.4.3 Acceptance Filtering

The acceptance filtering allows users to set the frame ID range that is allowed to be received.

4.2.4 MVB to Serial

As shown in the figure below, if the extended interface is a serial port, the protocol conversion between MVB and serial port can be realized by checking "Enable".

If the serial port and MVB interface establish forwarding relationship, its working mode must be set to UART-PPP mode.



4.3 UDP Configuration

4.3.1 Function Description

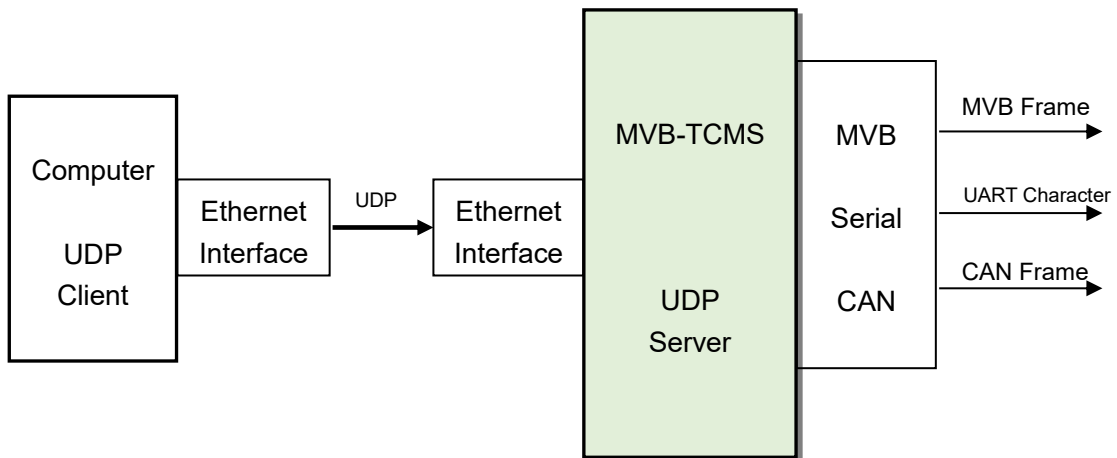
This configuration page implements the following configuration:

- UDP to interface: Configure UDP packets received by Ethernet to be forwarded to MVB, serial port or CAN port;
- Interface to UDP: Configure data received by MVB, serial port or CAN port to Ethernet.

4.3.2 UDP to Interface

When MVB-TCMS configures the source port of MVB process data, it can receive UDP packets containing the frame data of the source port from Ethernet, and then refresh the data buffer of PD port. When the MVB interface receives the process data request from the master station, the MVB-TCMS automatically sends the process data response with the latest data content.

MVB-TCMS can also receive UDP messages from the remote, convert them into UART data or CAN frame according to the configuration, and send it out from the serial port or CAN port.



Click the right-click menu of forwarding table can add or remove forwarding entries and establish multiple forwarding combinations.

UDP to Extended Interface

	UDP Rx Port	UDP Rx Multicast	Forward to Interface
1	8000	224.9.9.9	S1
2	9000		S2

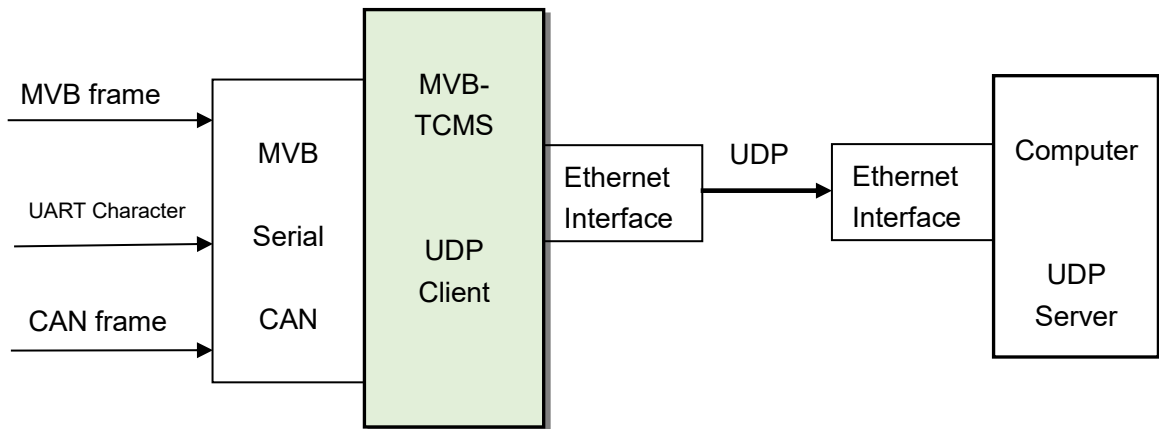
Add
Remove

If you want to receive multicast messages, you must fill in a valid multicast address in the 'UDP receive multicast address' table. If only unicast or broadcast messages are received, the form will not be filled in or filled in with 0.

4.3.3 Interface to UDP

When MVB-TCMS is configured with the sink port of process data, it can receive the frame data of PD port from MVB bus, then convert it into UDP message and forward it to the destination computer through Ethernet interface.

At the same time, MVB-TCMS can also receive UART strings and subcontract them through serial ports, receive CAN frames and group packets through CAN ports, convert the above data frames or packets to UDP packets, and then send them to remote devices through Ethernet ports according to configuration.



Click the right-click menu of forwarding table can add or remove forwarding entries and establish multiple forwarding combinations.

Extended Interface to UDP

	Rx from Interface	UDP Tx Destination IP	UDP Tx Destination Port
1	S1	192.168.2.80	8000
2	S3	224.9.9.9	9000

According to the application requirements, 'UDP send destination IP address' can be unicast, multicast or broadcast address.

If the Ethernet of MVB-TCMS is configured with dual IPs, multicast and whole network broadcast messages will be sent to two IP subnets at the same time.

4.4 MVB-PD Configuration

Click the right-click menu of MVB table can add or remove PD port configuration and establish up to 1024 PD port configurations.

MVB

	PD Port Type	PD Port	Port Size	Forward Cycle (ms)
1	<input type="radio"/> Sink Port	5000	2 bytes	100
2	<input type="radio"/> Sink Port	800	16 bytes	200
3	<input checked="" type="radio"/> Source Port	1200	32 bytes	
4	<input checked="" type="radio"/> Source Port	3600	2 bytes	

Dropdown menu for Port Size (row 4):

- 2 bytes
- 4 bytes
- 8 bytes
- 16 bytes**
- 32 bytes

Each PD port entry includes the following parameters:

- PD Port Type: Select Sink port or Source port;
- PD Port: Set port number 0 ~ 4095;
- Port Size: 2, 4, 8, 16, 32 bytes correspond to 0 ~ 4 of fcode;
- Forward Cycle: Valid when the port type is a sink port, indicating the period during which MVB PD data is periodically forwarded to Ethernet or Extended Interfaces.

4.4.1 Sink Port to Ethernet

The PD sink port of MVB interface and the forwarding configuration of Ethernet are created in the 'Extended Interface to UDP' table of the 'UDP' configuration page.

According to the forwarding cycle of PD port configuration, MVB-TCMS regularly sends UDP messages carrying PD sink port data.

If the forwarding cycle is set to 0, MVB-TCMS does not actively send UDP messages.

4.4.2 Sink Port to Serial

The PD sink port of MVB interface and the forwarding configuration of Serial are created in the 'MVB to Serial' table of the 'Extended Interface' configuration page.

According to the forwarding cycle of PD port configuration, MVB-TCMS regularly sends serial data carrying PD sink port data.

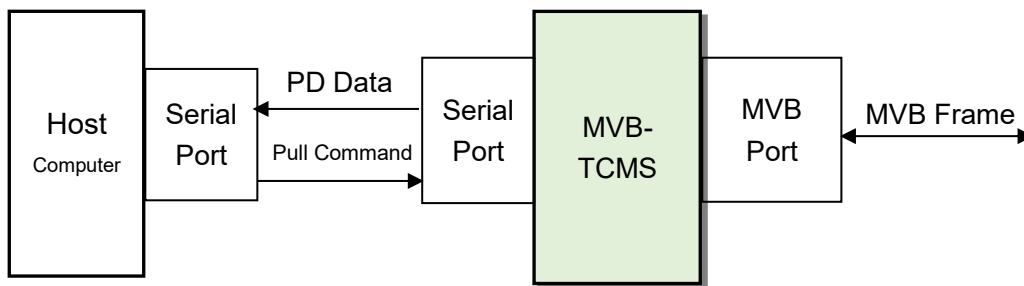
If the forwarding cycle is set to 0, send PD data in real time.

If the forwarding cycle is set to 65535, MVB-TCMS does not actively send serial data and waits for the host to pull the command before sending the MVB-PD data.

4.4.3 Serial Pull Mode

When the MVB-TCMS serial port receives the MVB data pull command issued by the host computer, it can passively send the process data requested by the command to the serial port, which is called the pull mode.

When the serial port works in RS-485 half duplex mode, if MVB-TCMS configures both PD source port and sink port, both MVB-TCMS and host computer have data sent to RS-485 bus. In this case, if the active transmission is based on the PD forwarding cycle, the transmission operation of MVB-TCMS and host computer may occur simultaneously, resulting in bus conflict. In order to avoid conflicts, the PD forwarding cycle can be set to 0. MVB-TCMS does not take the initiative to send, and only passively sends after receiving the pull command from host computer.



When the serial port works in the RS-232/422 full-duplex mode, the sending and receiving operations of the serial port can be carried out at the same time without conflict. The MVB can be transferred to the serial port by periodic active sending or pulling mode.

4.5 TRDP-PD Configuration

4.5.1 Function Description

This configuration page implements the following configuration:

- TRDP-PD Subscription: configure the parameters of subscription PD and the forwarding method of received PD data;
- TRDP-PD Publish: configure the parameters of publish PD and the source of PD data.

4.5.2 TRDP-PD Subscribe

MVB-TCMS receives the subscribed PD data through ETH1 and can choose to send it to the host computer through S1 ~ S4 interfaces or UDP.

COMID less than 1000 is reserved for the system, users must choose 1000 or more COMID.

TRDP PD Subscribe

	TRDP Rx COMID	TRDP Rx Multicast	
1	1000	0.0.0.0	
2	2000	224.10.10.10	

Data Forward to

Dest IP Address:

Dest UDP Port:

Dest Serial: S1 S2 S3 S4

As shown above, the subscription TRDP PD data is forwarded to the serial port S3 and the host with the destination IP of 192.168.2.80, where COMID 2000 is received through multicast.

When the destination IP or destination UDP port is configured to 0, the TRDP PD data is only forwarded from the selected serial port.

4.5.3 TRDP-PD Publish

MVB-TCMS receives the data to be published through UDP or other interfaces, and then sends them to the destination IP at the configured sending interval.

TRDP PD Publish

Data Receive from

Rx UDP Port:

Rx Multicast:

Rx Serial: S1 S2 S3 S4

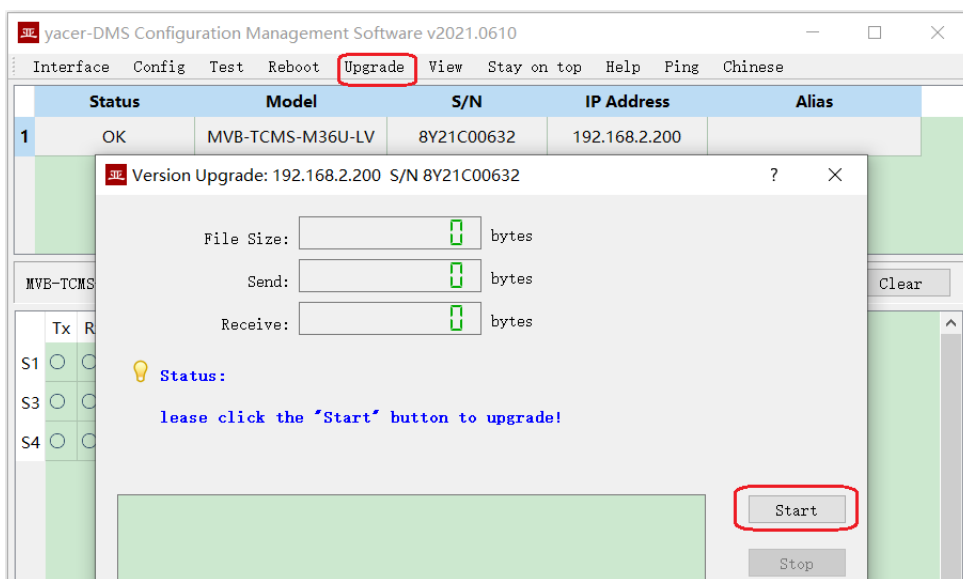
	TRDP Tx COMID	TRDP Tx Interval(ms)	TRDP Tx Destination IP	
1	4000	100	192.168.2.80	
2	5000	200	224.20.20.20	

5 System Maintenance

5.1 Firmware Version Upgrade

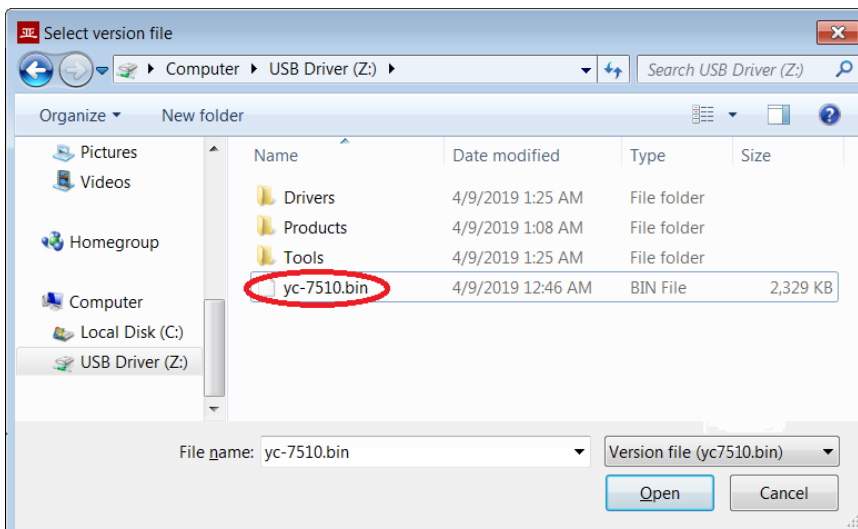
5.1.1 Start Upgrade

Click the “Upgrade” button on the toolbar to pop up the version upgrade dialog, and then click the “Start” button.



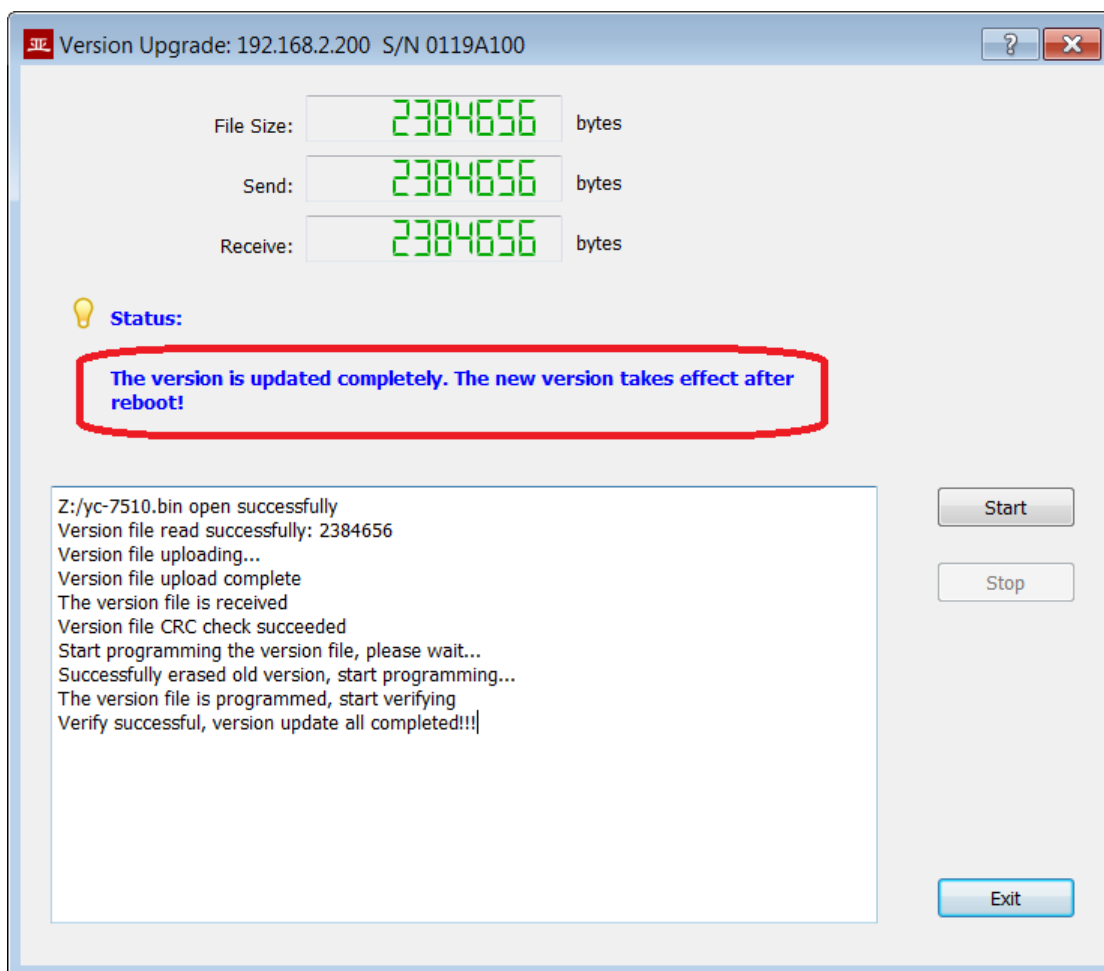
5.1.2 Select Version File

Pop up the “Select version file” dialog, and find the folder where the latest firmware version is stored, select the corresponding file, and click “Open” to start the update.



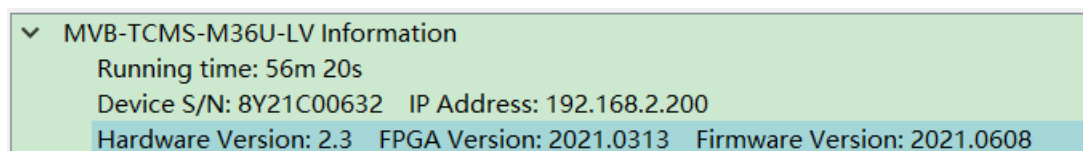
5.1.3 Complete Upgrade

When the page displays “Version upgrade complete” status, it indicates that the version upgrade is completed.



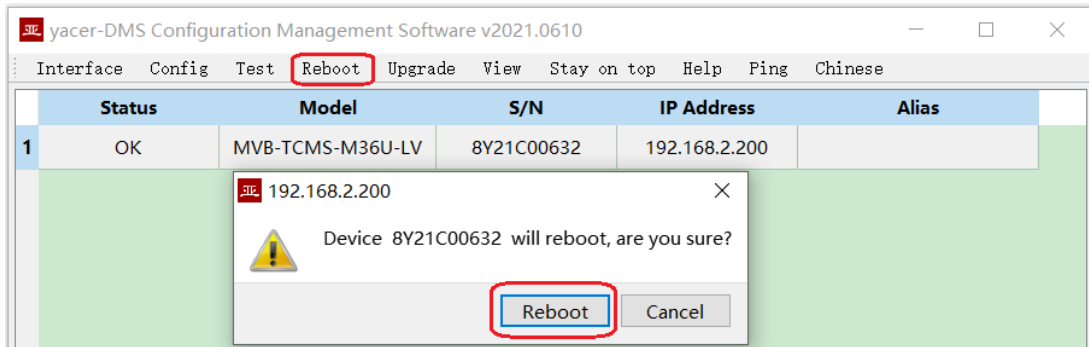
5.1.4 Confirm Upgrade

After the upgrade is completed, power up the device again, observe the version information in the statistical report, and determine whether the new version is successfully updated by the version date.



5.2 Reboot Device

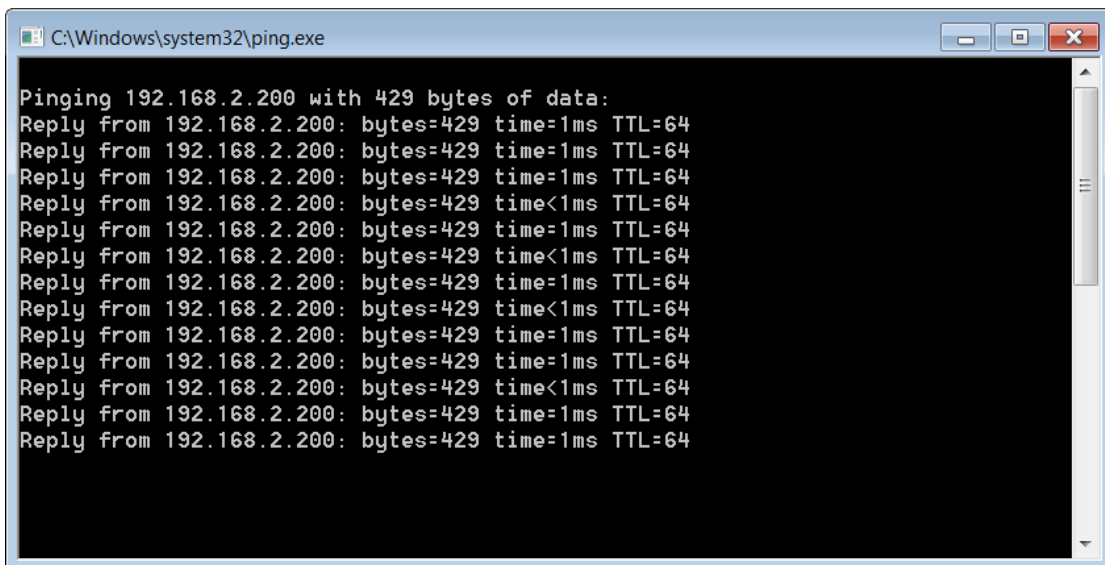
Click the “Reboot” button on the toolbar to pop up the device reboot dialog, and then click the “Reboot” button to reboot the device.



5.3 Ping

By clicking the "Ping" button on the toolbar, DMS automatically starts the ping command on the selected device to check whether the network connection between the configuration management computer and MVB-TCMS is working properly.

Before executing the Ping command, first make sure that the IP addresses of the computer and MVB-TCMS are in the same subnet.



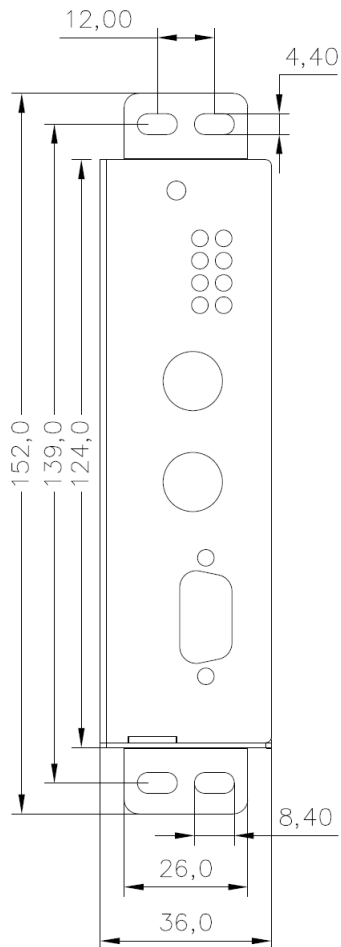
6 Mechanical Data

The material of the housing shell is stainless steel. The thickness of the sheet metal is 1mm.

Dimensions (Height x Width x Depth) = 124 x 36 x 104mm.

MVB-TCMS can be mounted directly using four M4 Screws.

Mounting hole diameter = 4.4mm.



7 Verification and Debugging of MVB

7.1 Auxiliary Equipment

- Yacer MVB-Analyzer;
- Computer;
- YC9T straight-through cable.

7.2 Auxiliary Software

The following software can be obtained by MVB-TCMS attached U-Disk or accessing <http://www.yacer.com.cn> 'Software' channel:

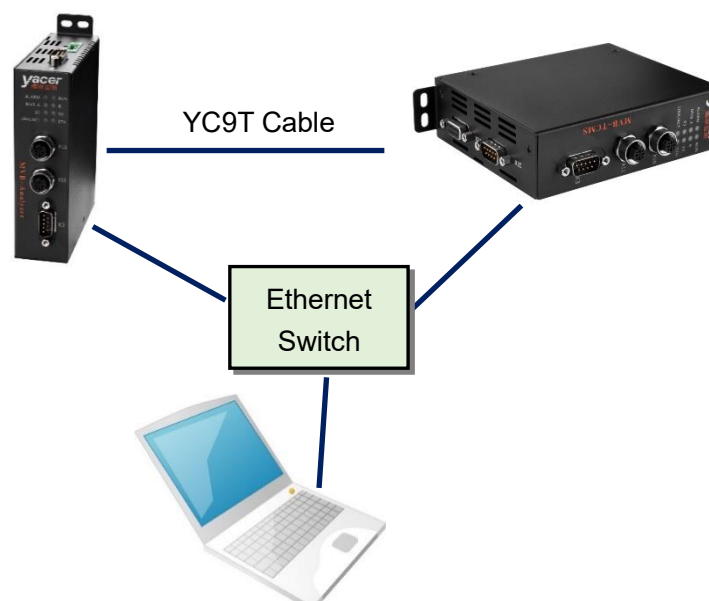
- *yacer-DMS* configuration management software;
- *MVB-Monitor* monitoring and analysis software;
- *MVB-UDP* debugging assistant.

7.3 Debugging and Testing Scheme

MVB-TCMS realizes MVB bus interconnection through YC9T cable and MVB-Analyzer, and computers, MVB-TCMS and MVB-Analyzer realize Ethernet interconnection through switches.

The MVB-Monitor software running on the computer can control the MVB-Analyzer to simulate the host, so as to realize the data transceiver of MVB interface of MVB-TCMS.

At the same time, the MVB-UDP debugging assistant software is running on the computer to simulate the communication between the host computer and the MVB-TCMS Ethernet interface.



8 Software Development

8.1 MVB Data Format Conversion

See *TCN-PACKET_Programming_Manual.pdf*.

8.2 TRDP Data Format Conversion

See *TCN-PACKET_Programming_Manual.pdf*.

8.3 CAN Data Format Conversion

See *CAN-UDP_Programming_Manual.pdf*.

About the Manual

- The manual is for reference only. If there is inconsistency between the manual and the actual product, the actual product shall prevail.
- We are not liable for any loss caused by the operations that do not comply with the manual.
- All the designs and software are subject to change without prior written notice. The product updates might cause some differences between the actual product and the manual. Please contact the customer service for the latest program and supplementary documentation.
- There still might be deviation in technical data, functions and operations description, or errors in print. If there is any doubt or dispute, we reserve the right of final explanation.
- Upgrade the reader software or try other mainstream reader software if the manual (in PDF format) cannot be opened.
- Please visit our website, contact the supplier or customer service if there is any problem occurring when using the device.
- If there is any uncertainty or controversy, we reserve the right of final explanation.